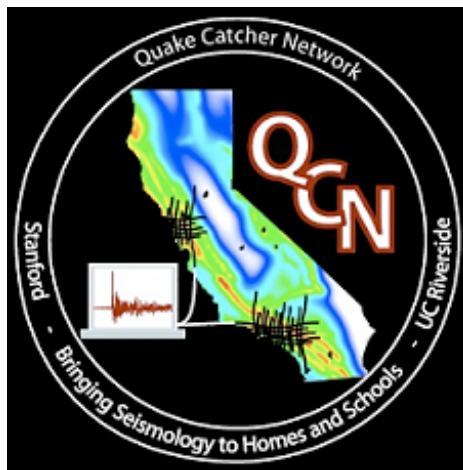


The Quake-Catcher Network: A Volunteer Distributed Computing Seismic Network

<http://qcn.stanford.edu>

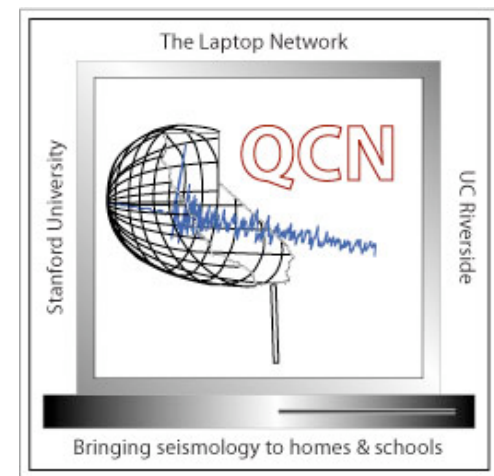


Carl Christensen
Stanford University

Elizabeth S. Cochran
UC Riverside

Jesse F. Lawrence
Stanford University

Jenny Saltzman
Stanford University

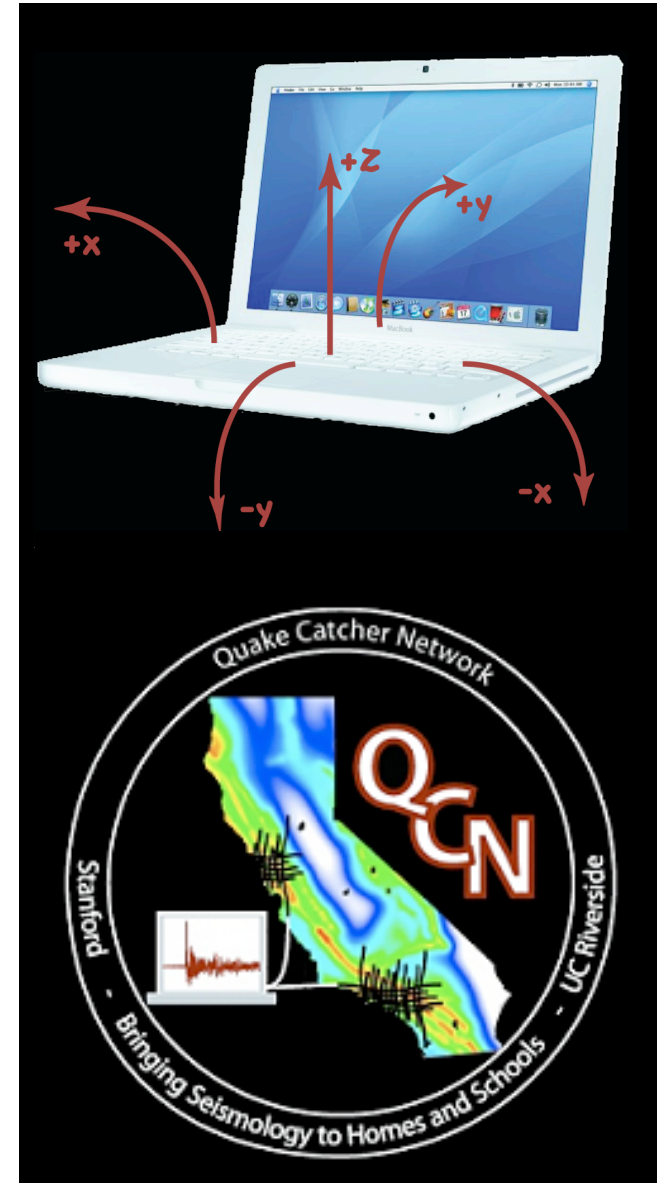


Ravi Jakka
UC Riverside

Candice Vance
UC Riverside

The Quake-Catcher Network

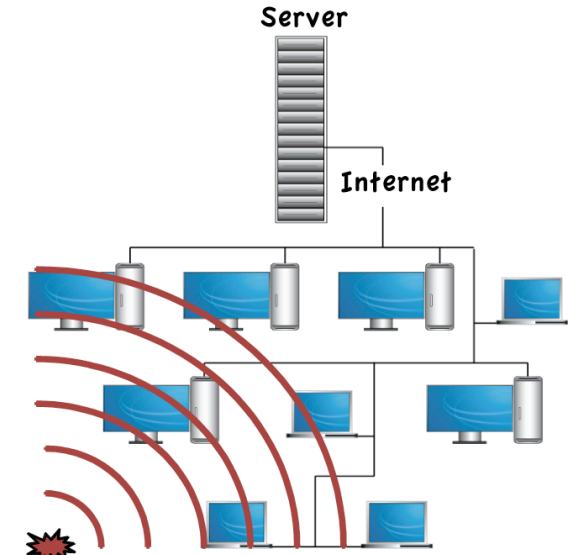
- **The Goal:** To network computers with internal or USB-connected accelerometers for rapid earthquake detection.
- **The Method:** We use distributed (volunteer) computing via BOINC to monitor internal or external (USB) sensors, connected to computers when they are not otherwise being used.



Volunteer Distributed Computing

Advantages:

- Low CPU and network infrastructure costs
- Network 1,000s to 100,000s of CPUs together rather than bridging 10s or 100s
- “Peer-to-Peer computing can provide 70 TFLOPS processing rate (which we may utilize for calcs someday)



Disadvantages:

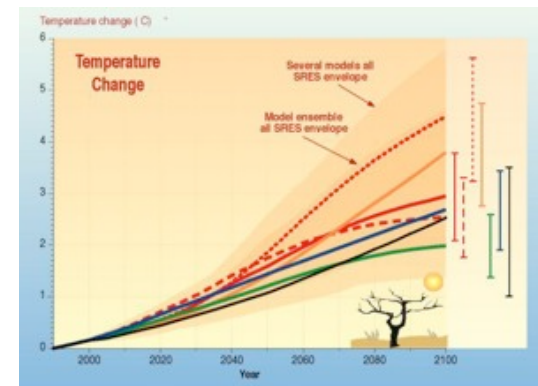
- Communication between CPUs is very slow
- CPUs cannot easily share memory
- CPUs have different clock speeds & different network speeds
- Processes can be interrupted by volunteer participants

What is Volunteer Distributed Computing For?

Large scientific computations that require very little inter-CPU communication.

– Signal detection or signal processing of many separate files for fast turnaround (each CPU analyzes a different signal and returns a single result).

- e.g. SETI@HOME
- Einstein@Home



– Serial problems that are run over and over (like Monte Carlo simulations).

- e.g.

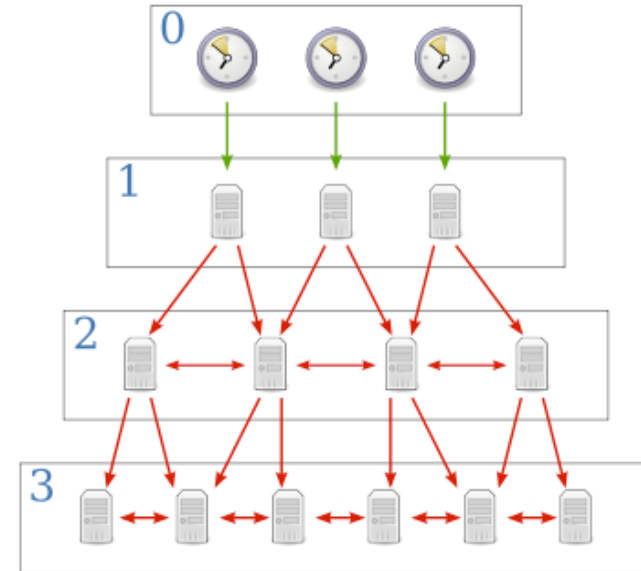
climateprediction.net

– Or now -- monitoring sensors!

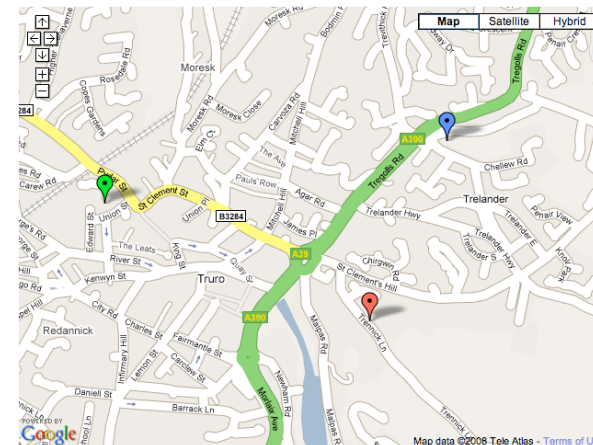
Time and Location

Network Time Protocol (NTP):

- Multi-tier system grounded to GPS Clocks, Atomic Clocks, Radio Clocks
- Peer-to-peer method often provides better than 0.1 second accuracy, often +/- 20 msec. [Frassetto et al., 2003]
- Non-system-level ntpdate client syncs to our reference Stanford server providing time offset



You can also (optionally) enter an IP (network) address to associate with map to this location, and help to sync up your triggers with the logging. We only store the first 3 bytes of your IP address, and never store any address information. All information is used solely to track seismic events. If information, we will use an IP/Lat/Lng lookup as a default; this will be shown at the bottom of this page as triggers occur.



Try to be as accurate as possible with your location using the Google Map provided. It will help us pinpoint events!

Select a different marker for each separate location you want to add - when you are done click the 'Update Info' button.

Tip: You can add a single entry (without an IP address) to always use a particular location for your machine (e.g. in case you always/only run QCN

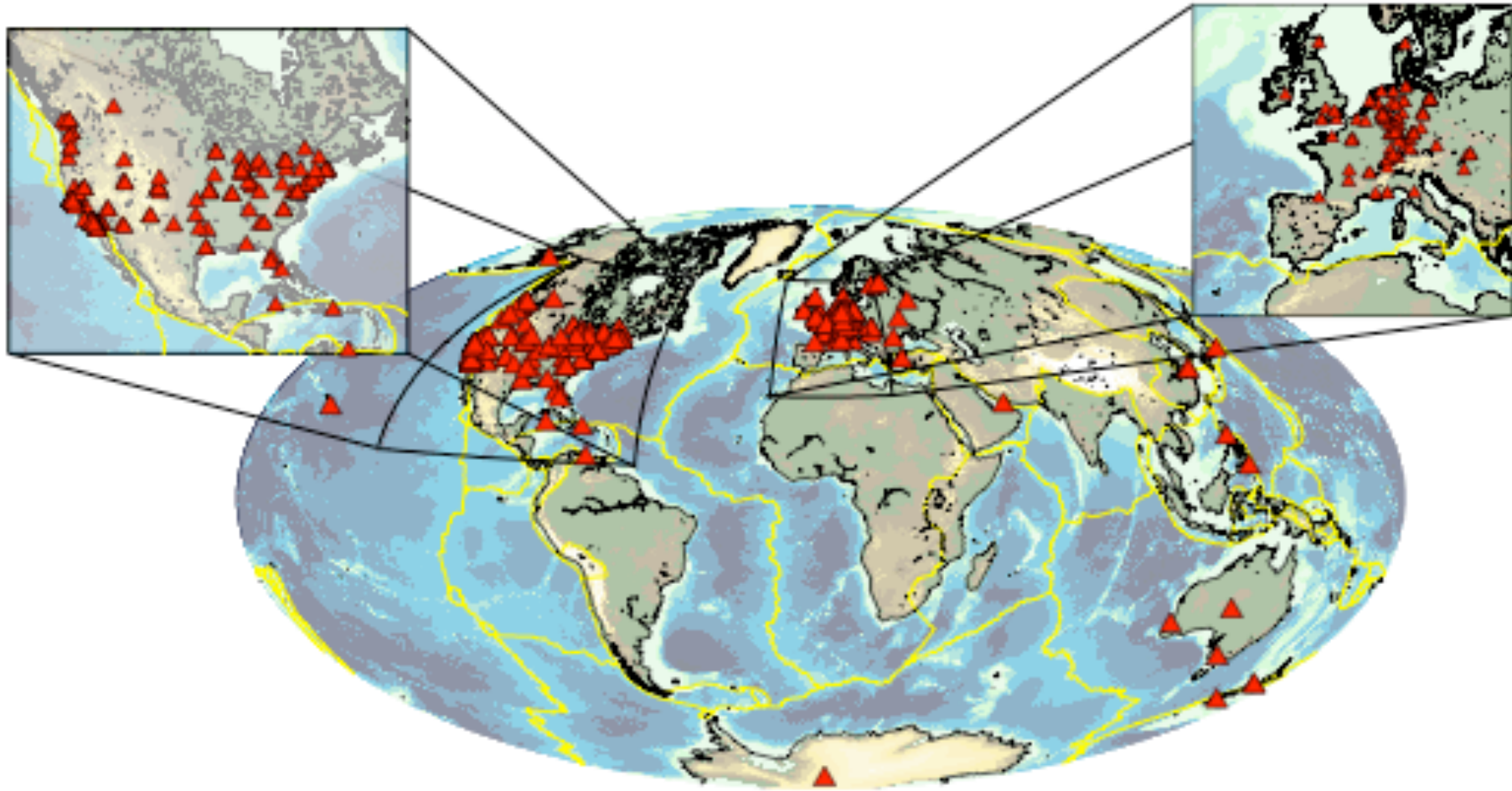
Note that the first row is set based on a guess based on your current IP address, this is not saved until you confirm by pressing the 'Update Info' button.

Select	Location Name (optional)	Latitude
	<input type="text" value="geoiip"/>	<input type="text" value="50.2617"/>
	<input type="text" value="work"/>	<input type="text" value="50.267069"/>

3-step Location System:

- Estimate location based on last known router (GeoIP / maxmind.com web service in BOINC scheduler)
- Google Maps Interface web page (lookup table in BOINC scheduler)
- Register at our “Where were you?” site a la USGS “Did you feel it?” site (future development).
- Future - USB accelerometers with GPS?

Expansion of the Network May, 2008



Triggering Algorithm

Significance Level Filter:

- Compare each point to the standard deviation of the signal in the long-term window prior to the trigger

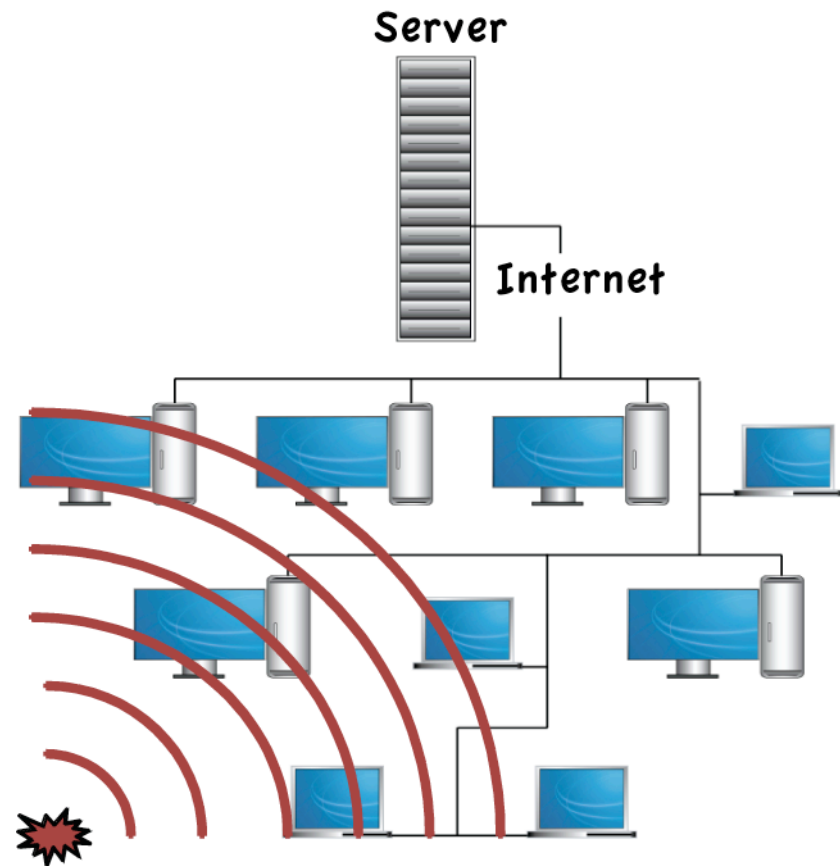
$$\sigma = \sqrt{\frac{1}{N} \sum_{i=1}^N (y_i - \bar{y})^2} \quad \sigma_i^2 = \sigma_{i-1}^2 + \frac{(y_i - \bar{y}_i)^2 - (y_{i-N-1} - \bar{y}_{i-N-1})^2}{N}$$

$$SL_i = \sqrt{(y_i - \bar{y}_i)^2} / (\sigma_i + wl)$$

- $SL = (|y_i| / s_i)$ provides the confidence level (e.g. $SL > 2$ gives a 95% confidence) that an emerging signal is statistically not representative of the prior long-term average (Gaussian)
- Extremely Fast, all CPU in the sensor monitoring loop (50 Hz)
- Computer records 1 minute before and 2 minutes after trigger to disk (SAC file I/O)

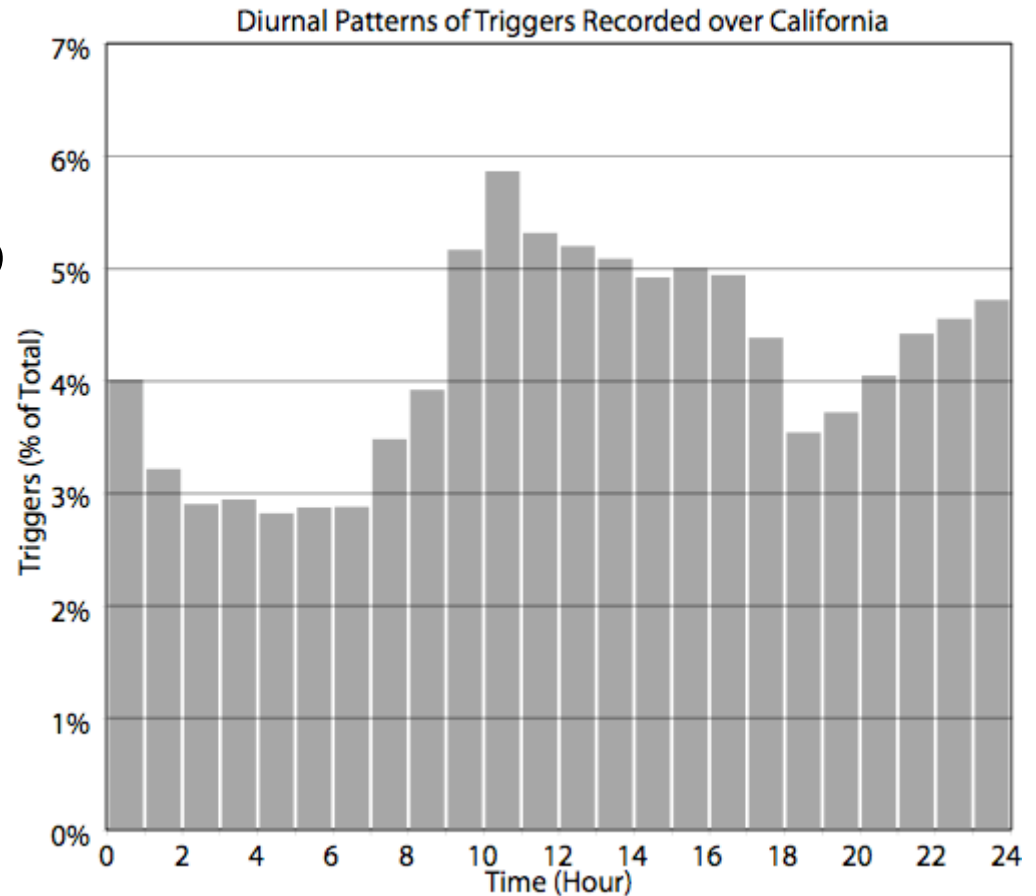
Earthquake Detection

- Probable earthquake detection when the QCN receives many triggers from a region
- Otherwise just people bumping their laptops
- For big earthquakes:
 - only strong vibrations will be detected
 - Only large earthquakes will cause consistent triggers across a region of the network

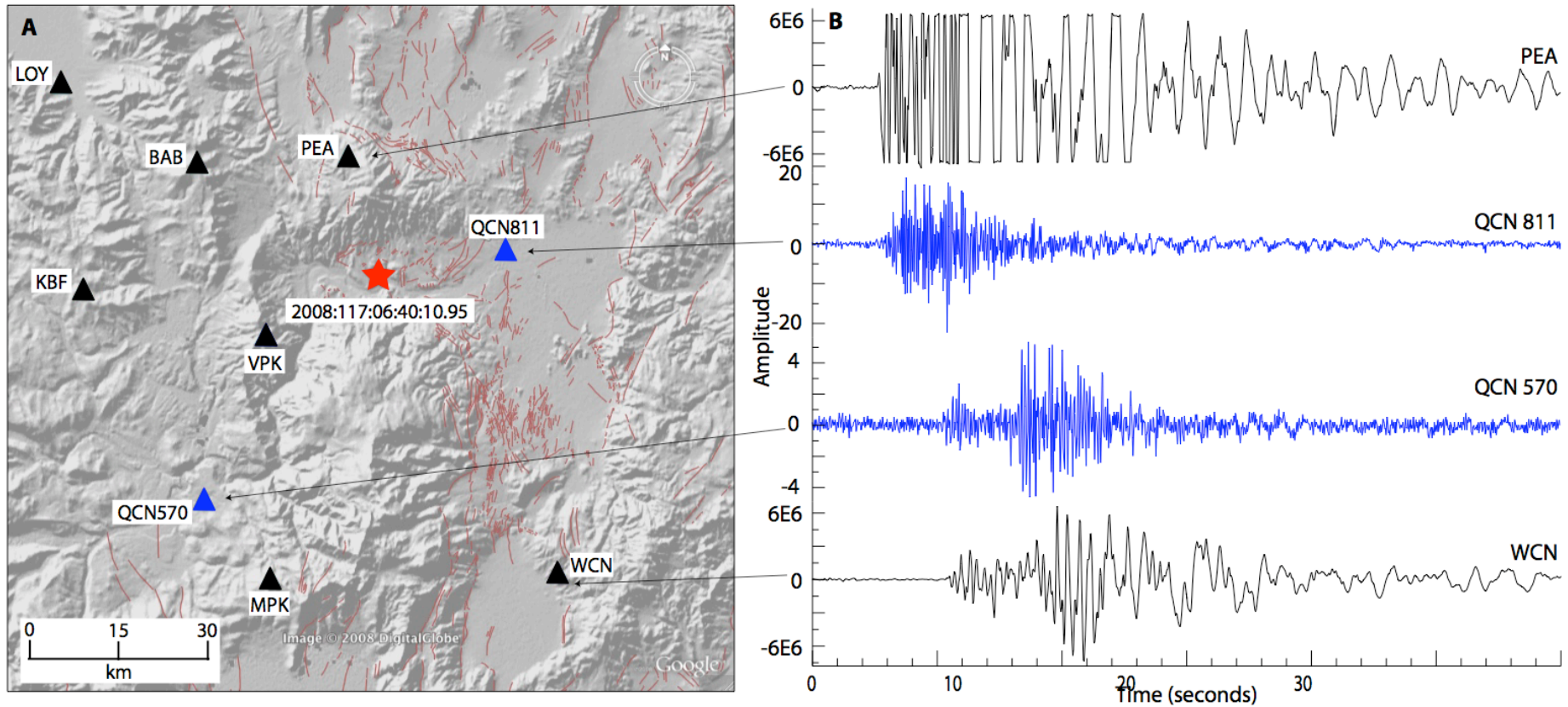


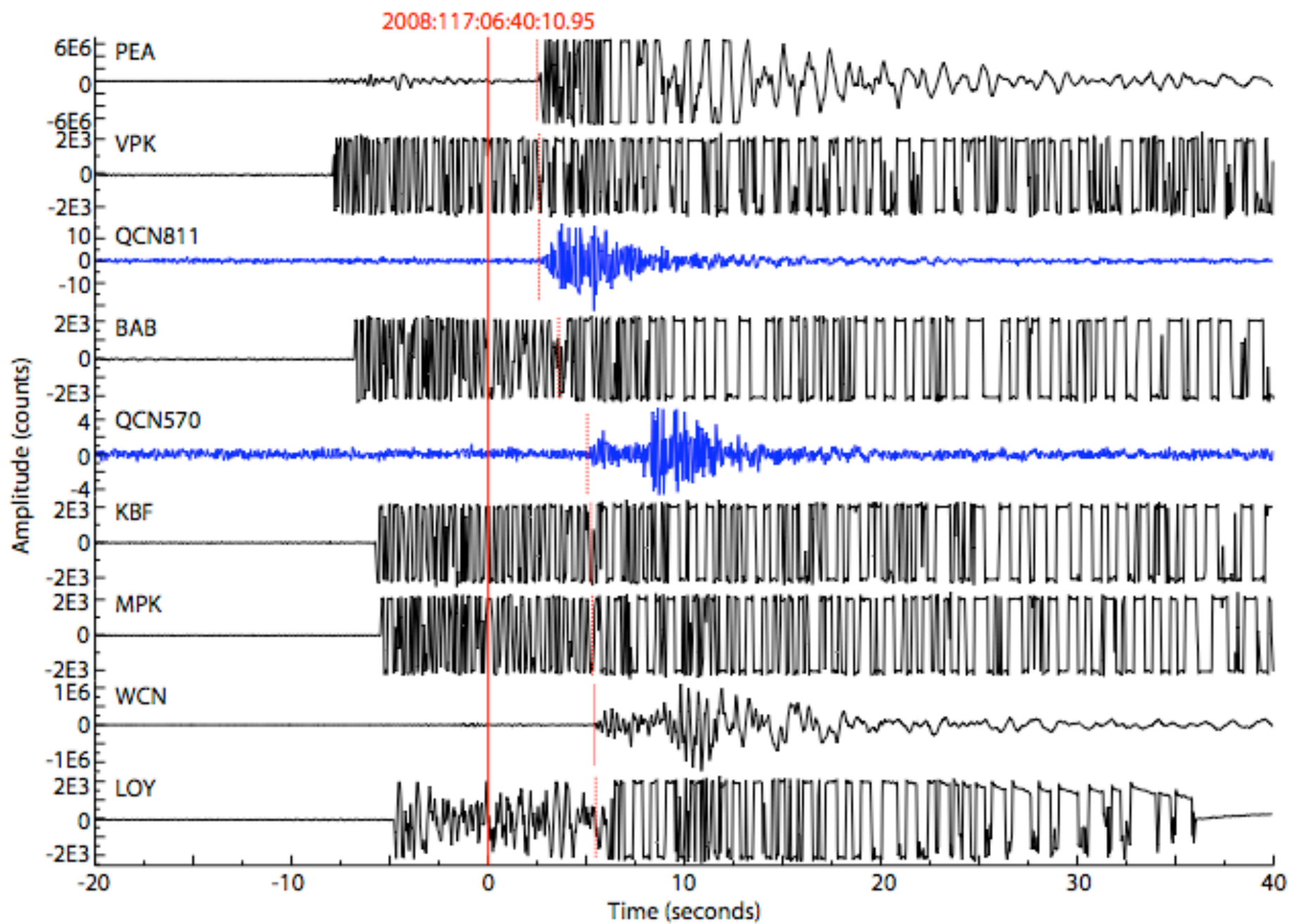
Trigger Statistics

- 1500+ laptops joined by September 2008
- Roughly 30-50 triggers per day from each laptop
- Number of triggers is roughly the same throughout the day (no large day/night difference)
- BOINC “trickles” – turnaround time $\sim 3-5$ s



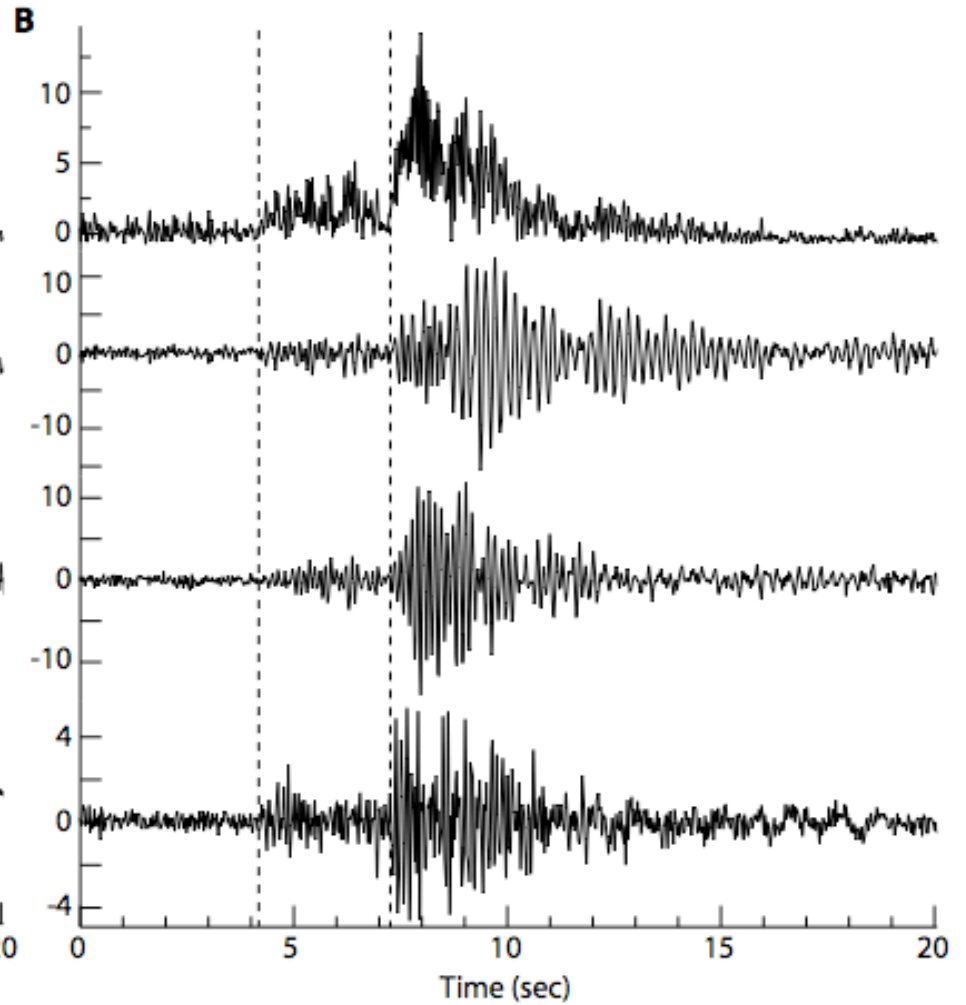
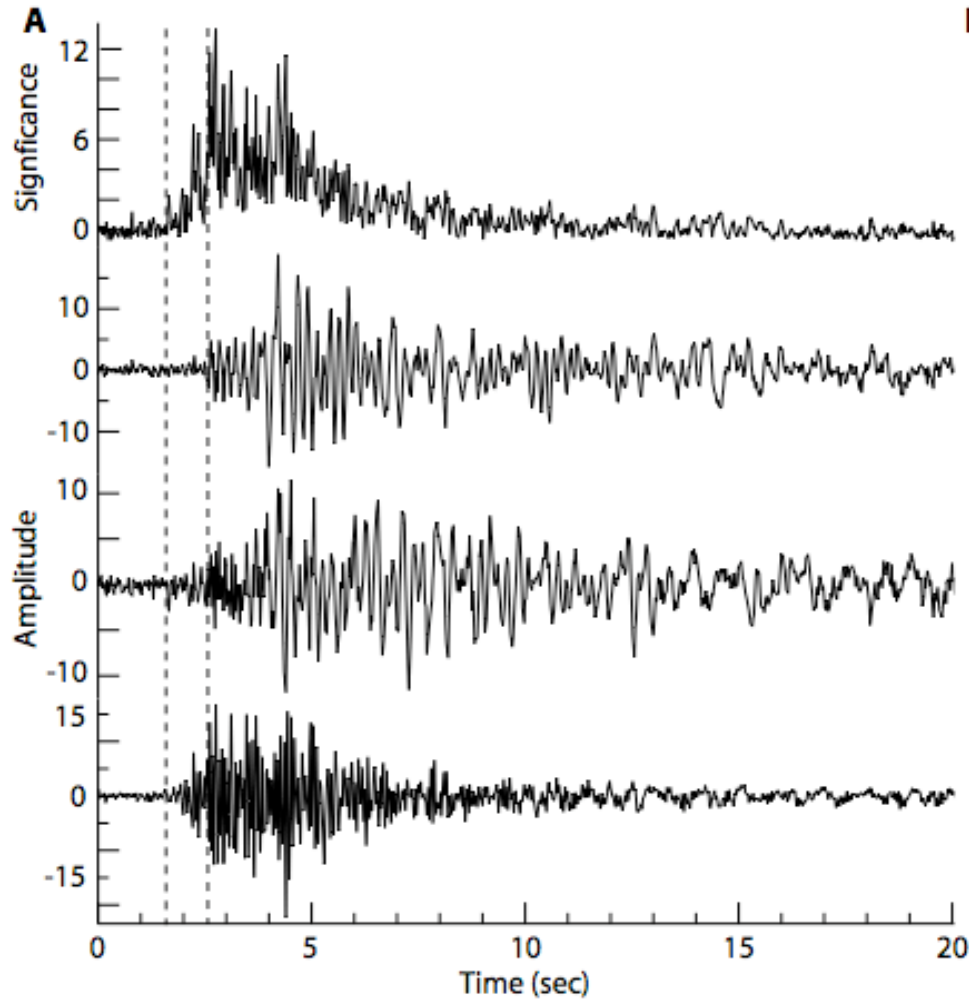
April 2008 Reno Earthquakes Captured!





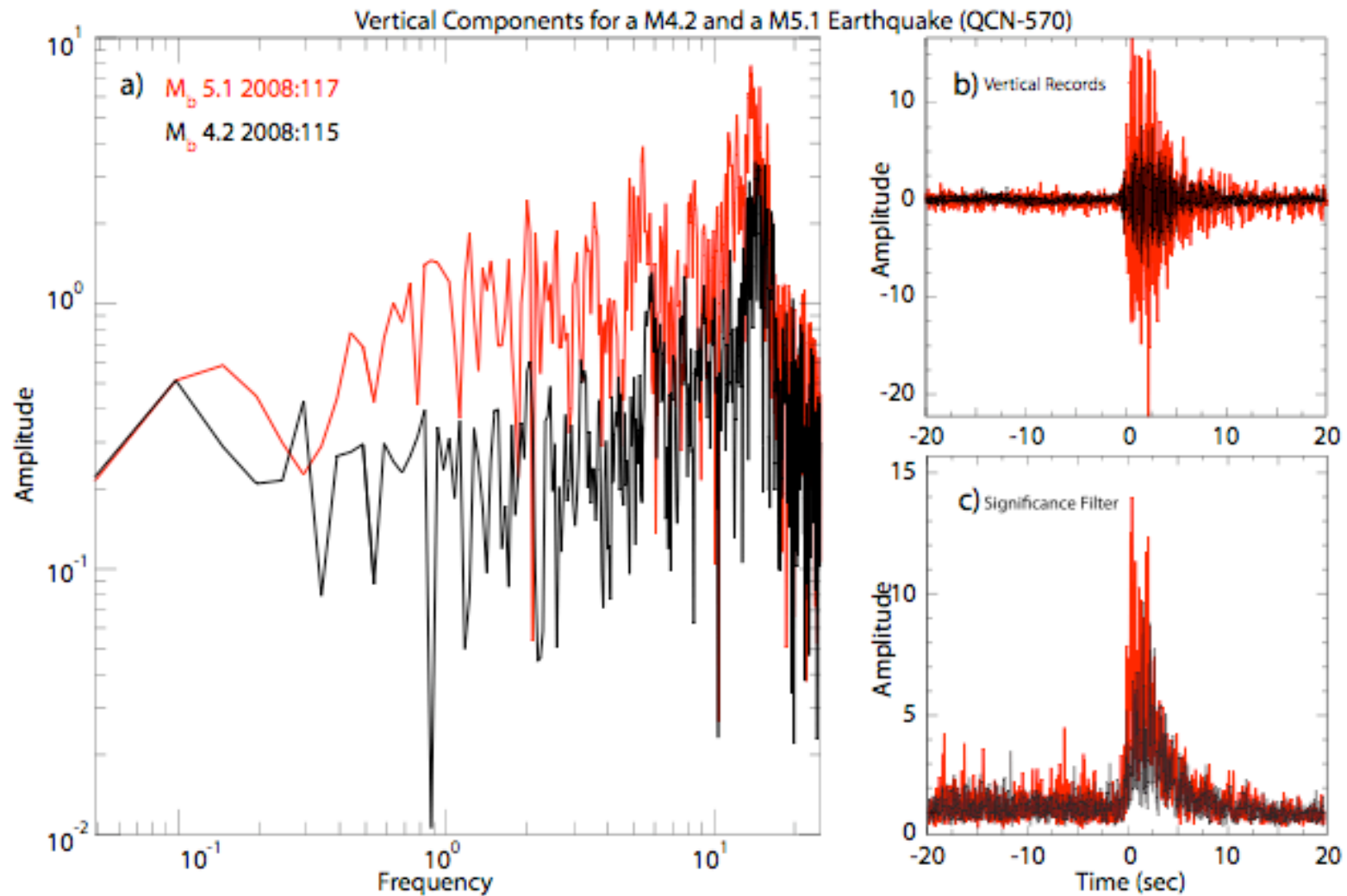
QCN 811 - 10.4 km

QCN 570 - 23.6 km



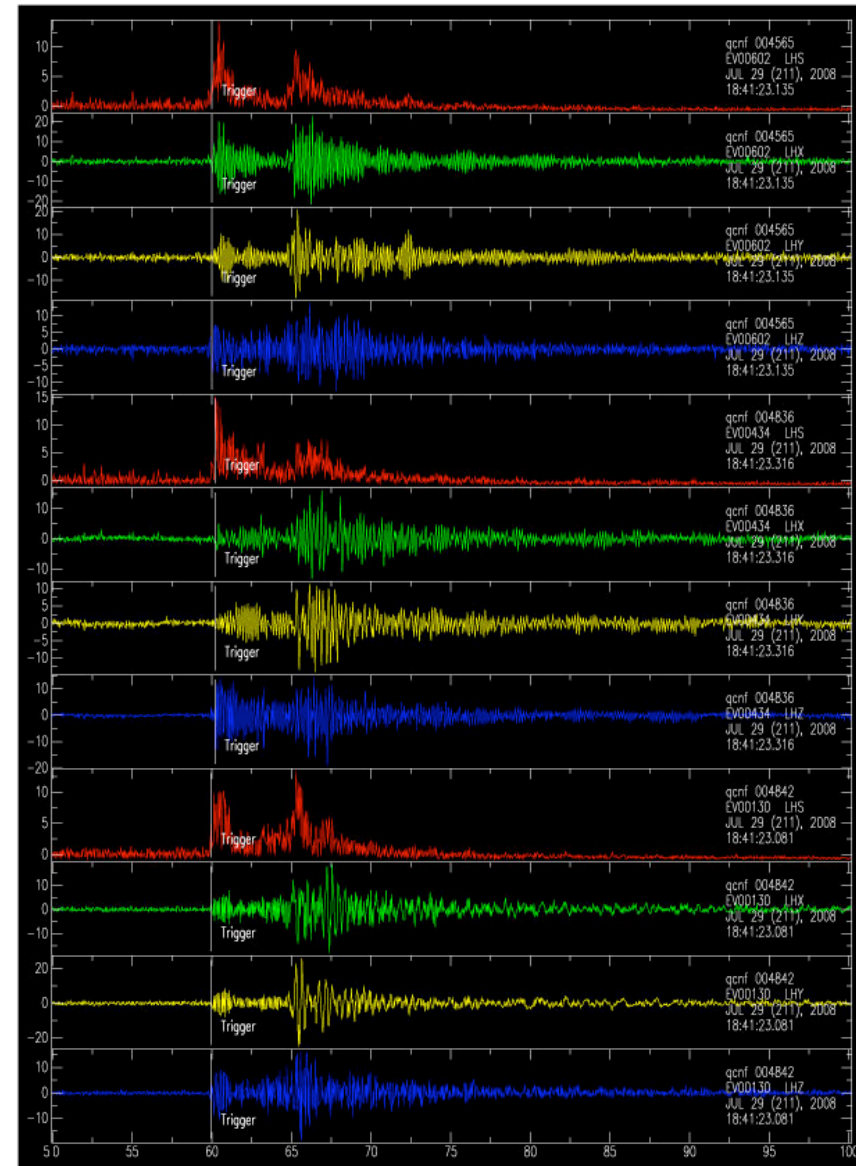
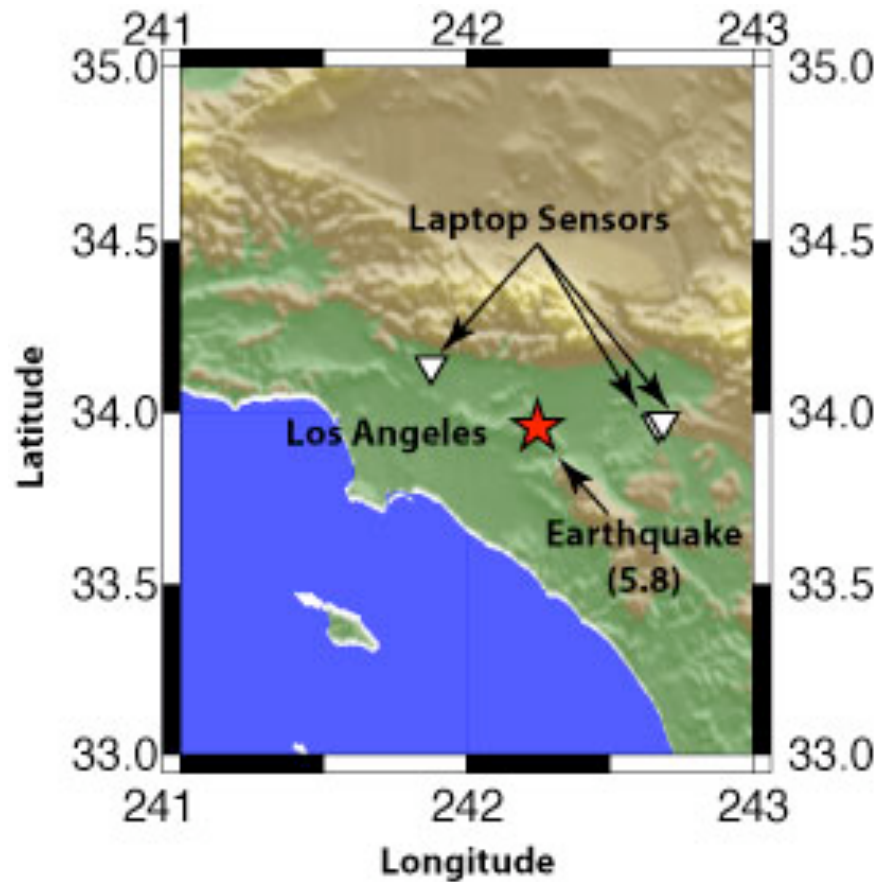
Response Comparison

M 5.1 and M 4.2 on QCN 811



July 29th LA Earthquake Captured!

http://qcn.stanford.edu/EVENTS/2008_211/



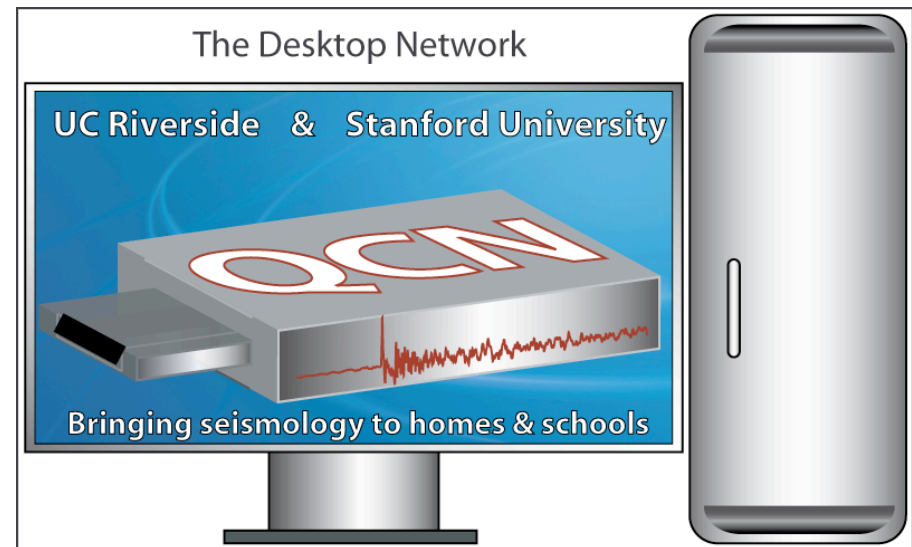
Building The Network

Laptop Network:

- | | |
|----------------------------|--------------------------|
| a) Planning & Development: | June, 2007 - March, 2008 |
| b) Beta-Testing Phase: | March, 2008 - Late 2008 |
| c) Expand & Monitor: | Summer, 2008 - |

Desktop Network:

- Purchase USB accelerometers for K-12 schools.
- Use same QCN codes
- Run continuously
- Provides a network backbone



Development Stage: Summer - Late 2008

Educational Outreach

- What we provide:
 - Classroom interactive OpenGL demo software based on BOINC screensaver (called “QCNLive”)
 - Seismology related in-class activities
 - Classroom USB Sensor
 - Classroom BOINC Software (for live monitoring/reporting)

